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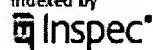
**1. Attitude control of hopping robot using angular momentum**

Morita, Y.; Ohnishi, K.;  
Industrial Technology, 2003 IEEE International Conference on  
Volume 1, 10-12 Dec. 2003 Page(s):173 - 178 Vol.1  
**IEEE CNF**

**2. Proceedings of IEEE International Conference on Control and Applications:**

Control Applications, 1994., Proceedings of the Third IEEE Conference on  
24-26 Aug. 1994  
**IEEE CNF**

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